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(71) Applicant (for all designated States except US):
DELAVAL HOLDING AB [SE/SE]; Box 39, S-147
21 Tumba (SE).

(72) Inventors; and

(75) Inventors/Applicants (for US only): PETTERSSON,
Maria [SE/SE]; Stockholmsvägen 60B, S-181 42 Lidingö
(SE). ANDRÉN DINERF, Johan [SE/SE]; c/o Reiner,
Strålgatan 23, S-112 63 Stockholm (SE).

(74) Agents: FRITZON, Rolf et al.; Kransell & Wennborg KB,
Box 27834, S-115 93 Stockholm (SE).

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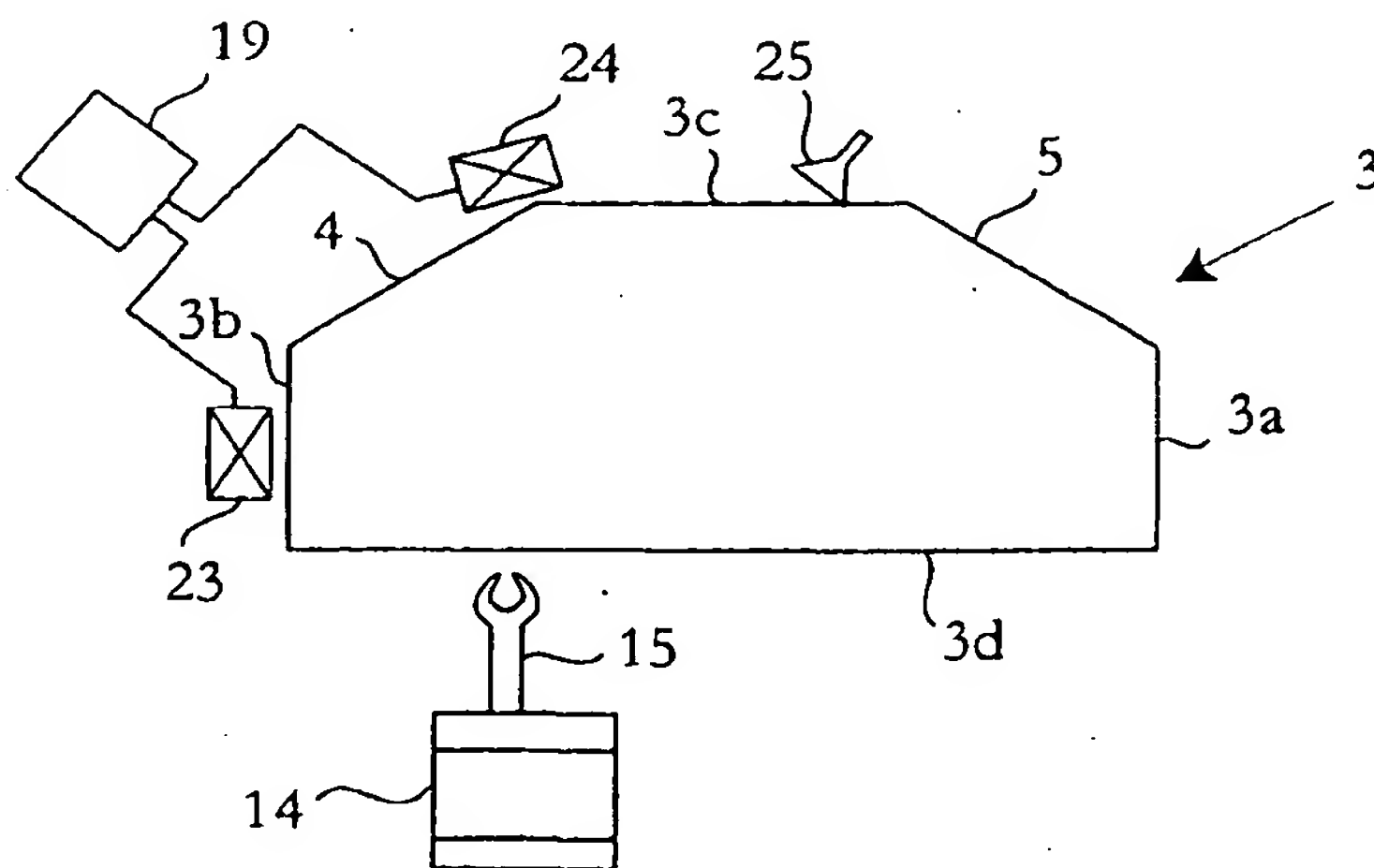
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(54) Title: ARRANGEMENT AND METHOD FOR DETERMINING POSITIONS OF THE TEATS OF A MILKING ANIMAL



(57) Abstract: An arrangement for deter-
mining positions of the teats of an animal is
provided in a robot-based milking system.
The arrangement comprises a camera pair
directed towards the teats of the animal for
repeatedly recording pairs of images, and an
image processing device for repeatedly de-
tecting the teats of the animal and deter-
mining their positions by a stereoscopic cal-
culation method based on the recorded pairs of
images. The image processing device may
be provided to initially determine the abso-
lute position of a teat of the milking sys-
tem, and to later determine the position of
the teat of the milking animal relative to the
robot arm or the teat cup repeatedly, wherein
the position of the teat of the milking animal
relative to the robot arm or the teat cup is
more exact than the absolute position. The

camera pair may be comprised of a pair of thermal or infrared cameras.

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